# The application of positive definite matrix in finding function extremum 

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#### Abstract

Function extremum is an important problem in mathematical analysis. In production and daily life, we all hope to reduce the consumption rate of production process and increase the utilization rate of products. We can attribute these practical problems to the extremum of function. It is easy to solve the extremum of simple function, but it is difficult to solve the extremum of multivariate function. Positive definite matrix plays a very important role in solving function extremum. It has a very broad prospect to use positive definite matrix to solve function extremum. This paper discusses the application of positive definite matrix in solving the extremum problem of multivariate function.


Index Terms-Function extremum, gradient, quadratic form, positive definite matrix, Hesse matrix.

## I. Introduction

Function plays a very important role in mathematics. At the same time, function is also a problem often encountered in solving mathematical problems [1]. The extreme value of function is a very important tool to solve mathematical problems.

Positive definite matrix plays a very important role in solving function extremum. It has a very broad prospect to use positive definite matrix to solve function extremum. This paper mainly discusses the application of positive definite matrix in solving the extremum problem of multivariate function, and obtains the method of using the gradient of function and Hesse matrix to find the extremum of multivariate function [2-8].

## II. The relationship between positive definite MATRIX AND FUNCTION EXTREMUM

In the process of solving some mathematical problems, we can realize that matrix is a very useful tool. Matrix plays a very important role in many fields. For example, modern mathematics, physics, engineering technology, computing technology and national economy. In fact, the matrix, especially the positive definite matrix, plays a more important role in finding the function extremum. Next, we discuss the relationship between positive definite matrix and function extremum.

In our learning process, we know that positive definite matrix plays a very important role in finding the function
extreme value. Through the positive definiteness of Hesse matrix, we can get the extremum of function and the existence point of extremum.

## A. Positive definite matrix and function extremum

Lemma 1 [6]. Assume $f(x)$ is a function with $n$ variables $x_{1}, x_{2}, \mathrm{~L}, x_{n}$, where $X=\left(x_{1}, x_{2}, \mathrm{~L}, x_{n}\right)^{T}$. if $f(x)$ has a first-order continuous partial derivative for each variable and $p_{0}=\left(x_{1}^{0}, x_{2}^{0}, \mathrm{~L}, x_{n}^{0}\right) \in R^{n}$ is a stationary point of $f(x)$, then the necessary condition for $f(x)$ to obtain the extreme value at point $p_{0}$ is $\operatorname{gradf}\left(p_{0}\right)=0$.

Lemma 2 [5]. Assume $Z=f(x, y)$ has a continuous second-order partial derivative in a neighborhood of point $\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)$, and $f^{\prime}{ }_{x}\left(x_{0}, y_{0}\right)=0, f_{y}^{\prime}\left(x_{0}, y_{0}\right)=0$. Let

$$
f^{\prime \prime}{ }_{x x}\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)=A, \boldsymbol{f}^{\prime \prime}{ }_{x y}\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)=\boldsymbol{B}, \boldsymbol{f}^{\prime \prime}{ }_{y y}\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)=\boldsymbol{C}
$$

Then we have the following results.
(1) When $A C-B^{2}>0$, the extreme value is taken at point $\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)$. Furthermore, the minimum value is obtained when $A>0$, while the maximum value is obtained when $A<0$.
(2) When $A C-B^{2}=0$, it is impossible to determine whether $\left(x_{0}, y_{0}\right)$ is the extreme point of $f(x, y)$ or not.
We can extend the above to multivariate functions as follows:
Lemma 3 [4] (Sufficient condition of extremum). Suppose that function $f(x)$ satisfies

$$
\nabla f(x)=\left(\frac{\partial f\left(x_{0}\right)}{\partial x_{1}}, \frac{\partial f\left(x_{0}\right)}{\partial x_{2}}, \Lambda, \frac{\partial f\left(x_{0}\right)}{\partial x_{3}}\right)=0
$$

in a neighborhood of point $x_{0} \in R^{n}$, then we have the following results.
(1) When $H\left(x_{0}\right)$ is a positive definite matrix, $f\left(x_{0}\right)$ is the minimum of $f(x)$.
(2) When $H\left(x_{0}\right)$ is a negative definite matrix, $f\left(x_{0}\right)$ is

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the maximum of $f(x)$.
(3) When $H\left(x_{0}\right)$ is an indefinite matrix, $f\left(x_{0}\right)$ is not the extreme value of $f(x)$.
From the lemma above, the sufficient condition for a binary function $z=f(x, y)$ to be minimal at point $\left(x_{0}, y_{0}\right)$ is $\frac{\partial f\left(x_{0}, y_{0}\right)}{\partial x}=\frac{\partial f\left(x_{0}, y_{0}\right)}{\partial y}=0$.
Therefore, we have

$$
\left.\begin{aligned}
& \boldsymbol{D}_{1}=\frac{\partial^{2} \boldsymbol{f}\left(\boldsymbol{x}_{0}, \boldsymbol{y}_{0}\right)}{\partial \boldsymbol{x}^{2}}>0, \\
& \left.D_{2}=\left|\begin{array}{|l}
\frac{\partial^{2} f\left(x_{0}, y_{0}\right)}{\partial x^{2}} \\
\frac{\partial^{2} f\left(x_{0}, y_{0}\right)}{\partial x \partial y} \\
\frac{\partial^{2} f\left(x_{0}, y_{0}\right)}{\partial x \partial y}
\end{array}\right| \frac{\partial^{2} f\left(x_{0}, y_{0}\right)}{\partial x^{2}} \right\rvert\,
\end{aligned} \right\rvert\,,\left[\begin{array}{ll}
\partial x^{2} & \left.\frac{\partial^{2} f\left(x_{0}, y_{0}\right)}{\partial x \partial y}\right]^{2}>0 .
\end{array}\right.
$$

## B. Some examples

These are the important definitions and lemmas listed above. Here are some examples.

Example 1. Find the extreme value of function $f\left(x_{1}, x_{2}, x_{3}\right)=x_{1}^{3}+x_{2}^{3}+x_{3}^{2}+12 x_{1} x_{2}+2 x_{3}$.

Solution. From the condition, we have

$$
\frac{\partial f}{\partial x_{1}}=3 x_{1}^{2}+12 x_{2}, \frac{\partial f}{\partial x_{2}}=2 x_{2}+12 x_{1}, \frac{\partial f}{\partial x_{3}}=2 x_{3}+2 .
$$

Let $\frac{\partial f}{\partial x_{1}}=0, \frac{\partial f}{\partial x_{2}}=0, \frac{\partial f}{\partial x_{3}}=0$, then we get the standing point $X_{0}=(0,0,1)^{T}, X_{1}=(24,-144,-1)^{T}$.
And because the second partial derivatives of $f(x)$ are

$$
\begin{aligned}
& \frac{\partial^{2} f}{\partial x_{1}^{2}}=6 x_{1}, \frac{\partial^{2} f}{\partial x_{1} \partial x_{2}}=12, \frac{\partial^{2} f}{\partial x_{1} \partial x_{3}}=2, \\
& \frac{\partial^{2} f}{\partial x_{2}^{2}}=2, \quad \frac{\partial^{2} f}{\partial x_{2} \partial x_{3}}=0, \frac{\partial^{2} f}{\partial x_{3}^{2}}=2,
\end{aligned}
$$

we get that Hesse matrix is

$$
H(x)=\left(\begin{array}{ccc}
6 x_{1} & 12 & 2 \\
12 & 2 & 0 \\
2 & 0 & 2
\end{array}\right)
$$

At point $X_{0}$, we can get

$$
H\left(X_{0}\right)=\left(\begin{array}{ccc}
0 & 12 & 2 \\
12 & 2 & 0 \\
2 & 0 & 2
\end{array}\right)
$$

The order principal subexpression of $H\left(X_{0}\right)$ is

$$
\operatorname{det} H_{1}=0, \quad \operatorname{det} H_{2}=\left|\begin{array}{cc}
0 & 12 \\
12 & 2
\end{array}\right|=-144<0
$$

,

$$
\operatorname{det} H_{3}=\operatorname{det} \boldsymbol{H}\left(\boldsymbol{X}_{0}\right)=-152<0
$$

So $H\left(X_{0}\right)$ indefinite, and then we get that $X_{0}$ is not the extreme point of the function.

At point $X_{1}$, we can get

$$
H\left(X_{1}\right)=\left(\begin{array}{ccc}
144 & 12 & 2 \\
12 & 2 & 0 \\
2 & 0 & 2
\end{array}\right)
$$

But the order principal formula of $H\left(X_{1}\right)$ is

$$
\operatorname{det} H_{1}=144>0
$$

$\operatorname{det} H_{2}=\left|\begin{array}{cc}144 & 12 \\ 12 & 2\end{array}\right|=144>0$,

$$
\operatorname{det} H_{3}=\left|\begin{array}{ccc}
144 & 12 & 2 \\
12 & 2 & 0 \\
2 & 0 & 2
\end{array}\right|=280>0
$$

So $H\left(X_{1}\right)$ is a positive definite matrix.
$X_{1}=(24,-144,-1)^{T}$ is a minimum, and the minimum is

$$
f\left(X_{1}\right)=f(24,-144,-1)=-6913 .
$$

Example 2. Find the extreme value of

$$
u=\sin x+\sin y+\sin z-\sin (x+y+z)
$$

where $0<x<\pi, 0<y<\pi, 0<z<\pi$.
Solution. Let

$$
\begin{aligned}
& u_{x}=\cos x-\cos (x+y+z)=0 \\
& u_{y}=\cos y-\cos (x+y+z)=0 \\
& u_{z}=\cos z-\cos (x+y+z)=0
\end{aligned}
$$

then we can easily get the only standing point $P\left(\frac{\pi}{2}, \frac{\pi}{2}, \frac{\pi}{2}\right)$.
From

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$$
\begin{aligned}
& \quad \boldsymbol{u}_{x x}=-\sin \boldsymbol{x}+\sin (\boldsymbol{x}+\boldsymbol{y}+\boldsymbol{z}) \\
& u_{x y}=\sin (x+y+z) \\
& u_{x z}=\sin (x+y+z) \\
& u_{y y}=-\sin y+\sin (x+y+z) \\
& u_{y z}=\sin (x+y+z) \\
& u_{z z}=-\sin z+\sin (x+y+z)
\end{aligned}
$$

we get $F=\left(\begin{array}{lll}-2 & -1 & -1 \\ -1 & -2 & -1 \\ -1 & -1 & -2\end{array}\right)$ at $\boldsymbol{P}$, so $\boldsymbol{P}$ is the maximum point, and the maximum value is $u(p)=4$.

The extremum of multivariate function can be determined by the positive definite form of Hesse matrix. This method can be used for ternary and above functions. However, by learning the sufficient conditions for the determination of extreme values of unary and bivariate functions, we can know that this method can also be used to determine the extreme values of unary and bivariate functions. Hesse matrix of one variable function and two variable function are first-order matrix and second-order matrix respectively. By using the positive definiteness of Hesse matrix of one variable function and two variable function, we can get the same conclusion as above.

Example 3. Discusses the extreme value of function

$$
Z=\frac{x^{2}}{2 p}-\frac{y^{2}}{2 q}(p>0, q>0) .
$$

Solution. It is easy to know that

$$
Z_{x}=\frac{x}{p}, \quad Z_{y}=-\frac{y}{p}
$$

Since the first partial derivative of function $\boldsymbol{Z}$ at point $(0,0)$ is zero. Therefore matrix

$$
A=\left(\begin{array}{ll}
Z_{x x}(0,0) & Z_{x y}(0,0) \\
Z_{y x}(0,0) & Z_{y y}(0,0)
\end{array}\right)=\left(\begin{array}{cc}
\frac{1}{p} & 0 \\
0 & -\frac{1}{q}
\end{array}\right)
$$

Therefore, from the discriminant law, function $\boldsymbol{Z}$ has no extremum.

## III. USING POSITIVE DEFINITE MATRIX TO SOLVE CONDITIONAL EXTREMUM PROBLEM

In the following discussion, we will list the methods of using positive definite matrix to solve the problem of conditional extremum according to Hesse matrix of function.

The following is the solution process of this kind of problem: If we want to find the extremum of function $\boldsymbol{f}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)$ with $\boldsymbol{n}$ arguments under condition $\boldsymbol{g}_{\boldsymbol{k}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)=0, \quad(\boldsymbol{k}=1,2, \Lambda, \boldsymbol{m})$, we can follow the following steps:
(1) Constructing Lagrange auxiliary function

$$
\begin{aligned}
& \boldsymbol{L}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{n}, \lambda_{1}, \lambda_{2}, \Lambda, \lambda_{m}\right) \\
& \quad=\boldsymbol{f}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda,, \boldsymbol{x}_{\boldsymbol{n}}\right)+\sum_{k=1}^{m} \lambda_{k} \boldsymbol{g}_{\boldsymbol{k}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda,, \boldsymbol{x}_{\boldsymbol{n}}\right) \\
& \text { (2) Suppose } \quad \frac{\partial L}{\partial x_{i}}=0 \quad(\boldsymbol{i}=1,2, \Lambda, \boldsymbol{n}) \quad, \quad \text { and }
\end{aligned}
$$

$$
\frac{\partial L}{\partial \lambda_{k}}=0(\boldsymbol{k}=1,2, \Lambda, \boldsymbol{m}) . \text { These equations are combined, }
$$ and the standing point $\left(\boldsymbol{x}_{1}^{0}, \boldsymbol{x}_{2}^{0}, \Lambda, \boldsymbol{x}_{n}^{0}, \lambda_{1}^{0}, \lambda_{2}^{0}, \Lambda, \lambda_{m}^{0}\right)$ is obtained by solving the equations, then $\boldsymbol{P}_{0}=\left(\boldsymbol{x}_{1}^{0}, \boldsymbol{x}_{2}^{0}, \Lambda, \boldsymbol{x}_{n}^{0}\right)$.

(3) Assume $\boldsymbol{F}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)$, the Hesse matrix of the constructor, be recorded as $H$, that is,

$$
\boldsymbol{H}=\left(\begin{array}{cccc}
\frac{\partial^{2} \boldsymbol{F}}{\partial x_{1}^{2}} & \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{1} \partial \boldsymbol{x}_{2}} & \cdots & \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{1} \partial x_{n}} \\
\frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{2} \partial \boldsymbol{x}_{1}} & \frac{\partial^{2} \boldsymbol{F}}{\partial x_{2}^{2}} & \cdots & \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{2} \partial \boldsymbol{x}_{n}} \\
\frac{\partial^{2} \boldsymbol{F}}{\partial x_{n} \partial x_{1}} & \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{n} \partial \boldsymbol{x}_{2}} & \cdots & \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}_{n}^{2}}
\end{array}\right) .
$$

(4) The coordinates of $\boldsymbol{P}_{0}=\left(\boldsymbol{x}_{1}^{0}, \boldsymbol{x}_{2}^{0}, \Lambda, \boldsymbol{x}_{n}^{0}\right)$ are substituted into $H$, and the corresponding numerical matrix is recorded as $H\left(P_{0}\right)$.

So we can get the following results.
(1) If $H\left(P_{0}\right)$ is a positive definite matrix, then under condition $\boldsymbol{g}_{\boldsymbol{k}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)=0, \boldsymbol{f}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)$ gets a minimum at $P_{0}$.
(2) If $H\left(P_{0}\right)$ is a negative definite matrix, then under condition $\quad \boldsymbol{g}_{\boldsymbol{k}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)=0, \boldsymbol{f}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}, \Lambda, \boldsymbol{x}_{\boldsymbol{n}}\right)$ gets the maximum at $P_{0}$.

Example 4. Find the extreme value of function $f(x, y)=x^{2}+y^{2}-3$ under condition $y=1+x$.
Solution. The first step is to construct the Lagrange function $L(x, y, \lambda)=x^{2}+y^{2}-3+\lambda(1+x-y)$. Solve the following system of equations

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$$
\left\{\begin{array}{c}
\frac{\partial L}{\partial x}=2 x+\lambda=0 \\
\frac{\partial L}{\partial y}=2 y-\lambda=0 \\
\frac{\partial L}{\partial \lambda}=1+x-y=0
\end{array}\right.
$$

to get $x=-\frac{1}{2}, \quad \mathrm{y}=\frac{1}{2}, \lambda=1$.
Next, determine whether $p_{0}\left(-\frac{1}{2}, \frac{1}{2}\right)$ is the extreme point or not. According to

$$
\begin{aligned}
F(x, y) & =x^{2}+y^{2}-3+1(1+x-y) \\
& =x^{2}+y^{2}+x-y-2
\end{aligned}
$$

we can get

$$
\begin{aligned}
& \frac{\partial \boldsymbol{F}}{\partial \boldsymbol{x}}=2 \boldsymbol{x}+1, \frac{\partial \boldsymbol{F}}{\partial \boldsymbol{y}}=2 \boldsymbol{y}-1, \frac{\partial^{2} \boldsymbol{F}}{\partial \boldsymbol{x}^{2}}=2, \\
& \frac{\partial^{2} \boldsymbol{F}}{\partial x \partial y}=\frac{\partial^{2} \boldsymbol{F}}{\partial y \partial x}=0, \frac{\partial^{2} F}{\partial y^{2}}=2 .
\end{aligned}
$$

Through these second-order partial derivatives, we can get that Hesse matrix $H\left(p_{0}\right)=\left(\begin{array}{ll}2 & 0 \\ 0 & 2\end{array}\right)$ is a positive definite matrix. Therefore, the function obtains the minimum value at point $\boldsymbol{P}_{0}\left(-\frac{1}{2}, \frac{1}{2}\right)$, and can find that the minimum value is $f\left(-\frac{1}{2}, \frac{1}{2}\right)=-\frac{5}{2}$.

## IV. CONCLUSION

Using the positive definiteness of Hesse matrix to judge the extremum of function, this method can be applied to univariate function, bivariate function and multivariate function. In this paper, we discuss how to use positive definite matrix to solve the problem of conditional extremum, and the extension of positive definite matrix decision theorem of multivariate function extremum. This makes us realize that using positive definite matrix to solve function extremum can be extended to other aspects. These conclusions are of great benefit to the future study.

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